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COMPARATIVE ANALYSIS OF RANDOM FOREST AND SUPPORT VECTOR MACHINE FOR LULC CLASSIFICATION IN TASHKENT REGION USING LANDSAT-8 IMAGERY

ABSTRACT

Accurate Land Use/Land Cover (LULC) classification is essential for effective environmental monitoring, sustainable agricultural management, and informed urban planning. With increasing land transformation driven by urbanization, deforestation, and climate variability, reliable classification methods are needed to support data-driven decision-making. This study presents a comparative analysis of two widely used machine learning algorithms — Support Vector Machine (SVM) and Random Forest (RF) — for LULC classification in the Tashkent Region, Uzbekistan, using Landsat-8 Operational Land Imager (OLI) data for the June–July of 2024. The workflow involved critical preprocessing steps, cloud filtering, and band selection, followed by classification using six dominant LULC classes: water, bare land, built-up areas, cropland, snow, and forest. Ground truth samples were used to train and validate the models. Accuracy assessment was conducted using a confusion matrix, and performance was evaluated based on Overall Accuracy (OA) and the Kappa Coefficient (KC). The results revealed that the SVM classifier slightly outperformed RF, achieving an OA of 96.78 % and a KC of 0.96, compared to RF's OA of 94.95 % and KC of 0.94. The superior performance of SVM is likely due to its effectiveness in handling high-dimensional feature spaces and separating non-linear class boundaries, especially in heterogeneous landscapes like Tashkent Region. While both algorithms showed strong potential, SVM demonstrated better precision in classifying cropland and forest areas. These findings highlight the importance of algorithm selection in remote sensing-based LULC studies. The study contributes to ongoing efforts to enhance land cover mapping accuracy using machine learning and offers valuable insights for land managers, urban developers, and environmental policymakers. Future research may consider the integration of multi-seasonal imagery, ancillary environmental data, and deep learning frameworks to further improve classification performance.

KEYWORDS: land use/land cover (LULC), random forest (RF), support vector machine (SVM), Landsat-8, remote sensing, Tashkent Region

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INTRODUCTION

Land Use/Land Cover (LULC) classification is a fundamental component of remote sensing and geographic information system (GIS) applications, playing a crucial role in environmental monitoring, natural resource management, and sustainable urban planning [Dash, Maity, 2023; Bhungeni et al., 2024]. Accurate LULC mapping is essential for understanding land dynamics, evaluating the impacts of climate change, and supporting decision-making in agriculture, forestry, and water resource management [Belgiu, Drăguț, 2016]. The increasing availability of satellite imagery, particularly from sensors like Landsat-8 Operational Land Imager (OLI), has facilitated large-scale and high-resolution LULC classification, allowing for more precise monitoring of landscape transformations. Various machine learning approaches have been employed to enhance classification accuracy, with Random Forest (RF) and Support Vector Machine (SVM) emerging as two widely used techniques due to their robustness and adaptability in remote sensing applications [Huang et al., 2002; Pal, 2005; Gislason et al., 2006; Mountrakis et al., 2011]. However, the comparative effectiveness of these methods for LULC classification in the Tashkent Region remains partly unexplored.

Uzbekistan, particularly the Tashkent Region, has been undergoing significant land cover changes due to rapid urbanization, agricultural expansion, and climate-induced environmental shifts [Teshaeiev et al., 2020; Aslanov et al., 2023; 2024]. As the capital and largest economic center of Uzbekistan, Tashkent has experienced considerable urban sprawl, leading to the conversion of agricultural and forested areas into built-up environments [Alikhanov et al., 2020; Aslanov et al., 2021; Erdanaev et al., 2022; Sharipov, Khayitmurodov, 2024]. Additionally, climate variability has influenced seasonal snow cover, water availability, and cropland productivity, necessitating accurate and up-to-date LULC classification for sustainable land management policies [Erdanaev et al., 2022; Farmonov et al., 2023]. Given these dynamics, implementing advanced machine learning-based classification techniques is essential for improving land cover monitoring in the region.

Traditional LULC classification methods, such as Maximum Likelihood Classification (MLC) and K-Nearest Neighbors (KNN), have been widely used in remote sensing applications [Foody, 2002; Mirzaei et al., 2023]. However, these approaches often suffer from limited classification accuracy, especially in complex landscapes with mixed land cover types [Foody, 2002]. Several studies have assessed the performance of machine learning algorithms for land cover mapping using satellite imagery [Farmonov et al., 2024]. For instance, [Belgiu, Drăguț, 2016] conducted a comparative analysis of RF and SVM, demonstrating that RF generally provides better classification accuracy due to its ability to handle high-dimensional datasets and reduce overfitting. Similarly, [Pal, 2005] explored the advantages of SVM in remote sensing and found that its performance varies depending on the study area's complexity and the chosen spectral features. More recent studies, such as those by [Zhang et al., 2022] have integrated spectral indices and multi-temporal imagery, highlighting the significance of proper feature selection in improving classification outcomes.

Indeed, in recent years, machine learning algorithms, particularly Random Forest (RF) and Support Vector Machine (SVM), have emerged as robust and efficient alternatives due to their ability to handle high-dimensional data and non-linear relationships [Pal, 2005; Rodriguez-Galiano et al., 2012]. Random Forest (RF) is an ensemble learning algorithm that constructs multiple decision trees to improve classification accuracy and reduce overfitting [Rodriguez-Galiano et al., 2012; Tian et al., 2016; Peng et al., 2023; Alikhanov et al., 2024]. It has been widely adopted in LULC classification studies due to its robustness in handling spectral variability and missing data [Breiman, 2001]. Several studies have demonstrated RF's superior performance in remote sensing applications, particularly in heterogeneous landscapes [Gislason et al., 2006; Belgiu, Drăguț, 2016]. Support Vector Machine (SVM), on the other hand, is a supervised learning algorithm that finds an optimal hyperplane to separate different land cover classes [Vapnik, 2000]. It is particularly effective for small sample sizes and high-dimensional datasets and has been successfully

applied in various LULC studies [*Huang et al., 2002; Mountrakis et al., 2011*]. However, SVM's performance is highly dependent on parameter tuning, and it may struggle with complex class distributions and overlapping spectral signatures [*Maxwell, Fang, 2018*].

Several comparative studies have evaluated RF and SVM for LULC classification using satellite imagery, highlighting their advantages and limitations. While RF has been found to be computationally efficient and accurate, SVM often performs well in cases where clear class separability exists [*Adam et al., 2010*]. However, limited research has been conducted on the application of these algorithms in Uzbekistan, specifically in the Tashkent Region, where land cover patterns are rapidly evolving. Given the increasing demand for high-accuracy LULC classification in the Tashkent Region, this study aims to compare the performance of RF and SVM for LULC classification using Landsat-8 OLI imagery. Evaluate the classification accuracy of each model by assessing Overall Accuracy (OA) and Kappa Coefficient (KC). Identify the most suitable algorithm for large-scale land cover mapping in Uzbekistan, focusing on urban, snow, bare land, forest, water, and croplands. Contribute to existing knowledge on machine learning-based LULC classification in Uzbekistan by providing a case study in the Tashkent Region.

Landsat-8, launched by NASA and the USGS in 2013, provides high-quality multispectral and thermal data, making it an essential resource for LULC analysis. Compared to previous Landsat missions, Landsat-8 offers improved radiometric resolution (16-bit), enhanced signal-to-noise ratio, and two additional spectral bands, the Coastal/Aerosol band (B1) and the Cirrus band (B9) — which improve atmospheric correction and land cover discrimination. The Operational Land Imager (OLI) sensor, capturing data across nine spectral bands, ensures high accuracy in distinguishing vegetation, water bodies, urban areas, and bare land. Additionally, the satellite's 30-meter spatial resolution and 16-day revisit cycle provide an optimal balance between spatial coverage and temporal frequency, making it suitable for both seasonal and long-term LULC monitoring. Compared to Sentinel-2, which has higher spatial resolution but a shorter historical archive, Landsat-8's long-term data availability supports multi-year trend analysis in rapidly changing environments like Tashkent [*Schmidt et al., 2016; Korhonen et al., 2017; Sajib, Wang, 2020*].

This study aims to enhance the understanding of machine learning applications in LULC classification and provide valuable insights for urban planners, environmental managers, and policymakers in Uzbekistan. By comparing two classification algorithms, this research seeks to improve land cover monitoring efforts and support sustainable land management strategies in the region.

RESEARCH MATERIALS AND METHODS

The study was conducted in the Tashkent Region, which serves as the capital and the most populous administrative division of Uzbekistan. Covering an area of approximately 15 300 km², the region is strategically significant due to its economic, agricultural, and environmental importance. Tashkent is in the northeastern part of the country, bordered by Kazakhstan to the north and the Syr Darya River to the west, with varying topography that includes plains, foothills, and mountainous areas in the east, where it meets the Chatkal Mountain Range [*Alikhanov et al., 2020*].

Tashkent experiences a continental climate, characterized by hot, dry summers and cold winters, leading to significant seasonal variations in land cover. The average temperature in summer can exceed 35 °C, while winter temperatures often drop below freezing, with occasional snowfall. These climatic variations contribute to seasonal shifts in vegetation, changes in water availability, and fluctuations in snow cover, which must be accounted for in LULC classification efforts [*Erdanaev et al., 2022; Sharipov, Khayitmurodov, 2024*].

The land cover of the Tashkent Region has been rapidly changing due to multiple factors, including urbanization, agricultural expansion, deforestation, and climate-induced environmental changes [*Aslanov et al., 2021*]. The growth of urban areas is primarily driven by population increase, infrastructure development, and industrialization, leading to the conversion of agricultu-

ral lands and natural vegetation into built-up environments. Meanwhile, agriculture remains a dominant land use in the region, with large areas dedicated to wheat, cotton, orchards, and vegetable cultivation, often supported by extensive irrigation systems fed by the Chirchik River and other smaller tributaries [Gafforov et al., 2020]. The diversity in land cover types, coupled with rapid urban and environmental transformations, makes the Tashkent region an ideal study site for LULC classification using remote sensing techniques.

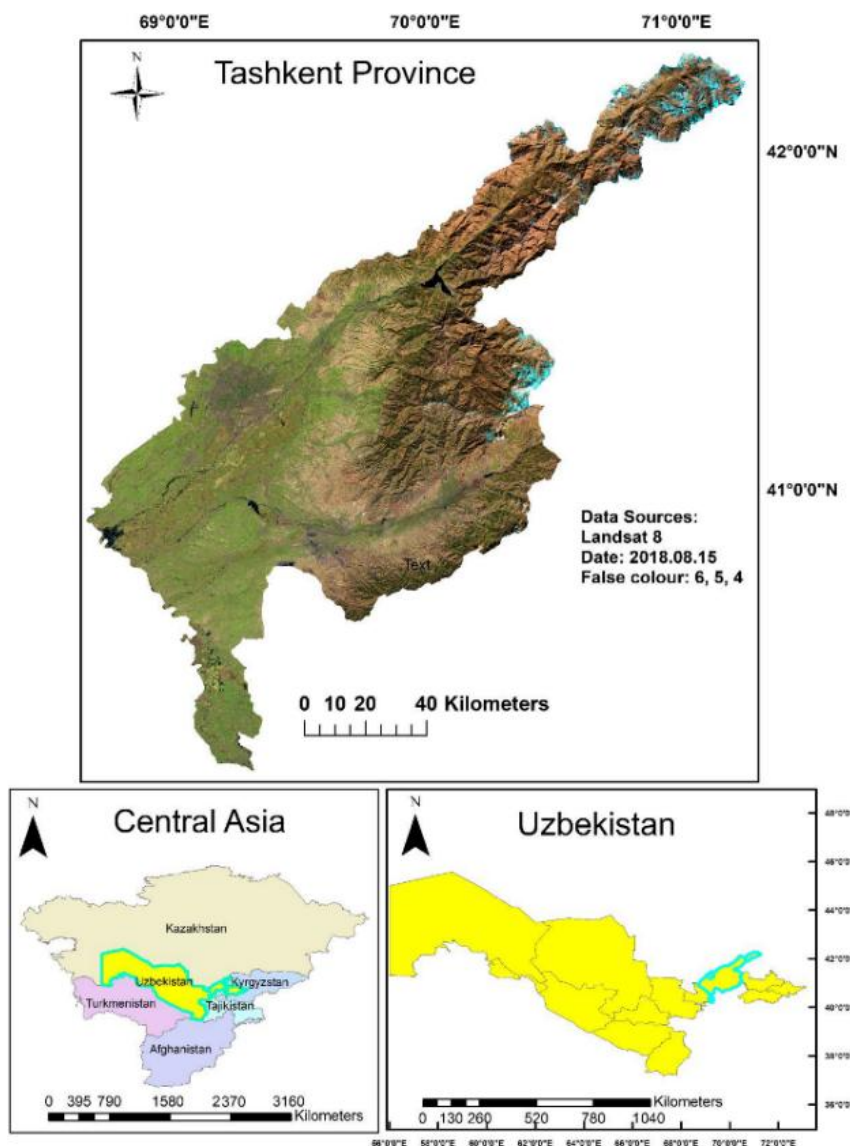


Fig. 1. The study area location map [Erdanaev et al., 2022]

The study categorizes the landscape of the Tashkent Region into six major Land Use/Land Cover (LULC) classes on their distinct spectral, spatial, and environmental characteristics. These classes include urban areas, croplands, bare land, forests, water bodies, and snow cover. Each category represents a significant component of the region’s land dynamics, influenced by urbanization, agricultural practices, natural ecosystems, and climatic variations. The classification provides insights into land cover distribution, resource management, and environmental sustainability. The table below summarizes the key LULC classes, their descriptions, and their environmental significance.

Table 1. Land Use/Land Cover (LULC) Classes in the Tashkent Region

LULC Class	Description	Key Characteristics	Environmental Importance
Urban Areas	Built-up environments include residential, commercial, and industrial zones	High-density buildings, paved surfaces, minimal vegetation	It affects local climate (heat island effect), reduces permeable surfaces, and impacts air quality
Croplands	Agricultural fields cultivated with various seasonal and perennial crops	Dominated by wheat, cotton, and horticultural crops; irrigated and rain-fed agriculture	Essential for food security, affected by climate and land-use policies
Bare land	Unvegetated surfaces including exposed soil, rocky areas, and degraded lands	Found in construction zones, deforested areas, and eroded landscapes	Indicator of land degradation and soil erosion; potential for land reclamation
Forests	Natural and plantation forests provide ecological and economic benefits	Found mainly in mountainous regions; composed of juniper, pine, and mixed deciduous trees	Helps in carbon sequestration, biodiversity conservation, and soil erosion prevention
Water Bodies	Lakes, rivers, reservoirs, and irrigation channels critical for the region's hydrology	Includes Chirchiq River, Charvak Reservoir, and artificial irrigation networks	Supports agriculture, drinking water supply, and hydropower generation
Snow Cover	Seasonal or permanent snow-covered surfaces, mainly in high-altitude areas	Observed during winter months; fluctuates with climate variability	Important for water resource availability, glacier monitoring, and climate change studies

Satellite data

This study utilized Landsat-8 Operational Land Imager (OLI) imagery, a widely used satellite dataset for remote sensing applications. Landsat-8 OLI provides high-quality multispectral data suitable for Land Use/Land Cover (LULC) classification. The key specifications of the Landsat-8 OLI sensor are as follows:

- spatial resolution: 30 meters for multispectral bands;
- temporal resolution is 16-day revisit cycle, ensuring regular data updates;
- spectral coverage has contained 11 bands, including visible, near-infrared (NIR), short-wave infrared (SWIR), and thermal infrared (TIR) bands, allowing for detailed land cover differentiation.

Landsat-8 data and scene selection

Landsat-8 Collection 2 Level 2 surface reflectance scenes covering the Tashkent study area were retrieved from Google Earth Engine (GEE). Images were filtered to the period 2024-06-01 to 2024-07-30 and constrained to scenes with cloud cover <30 %, resulting in 12 scenes (Table 2). Because the scenes partially overlap (adjacent WRS path/row tiles), a per-pixel median composite

of the filtered images was computed and used as the input raster for classification. The June–July window corresponds to the regional peak growing season, maximizing spectral separability of major classes (cropland, forest, grassland). Median compositing reduces residual cloud/shadow effects and radiometric noise; however, compositing across a multi-week window can smooth short-term phenological differences (e. g., early wheat harvest vs. later cotton growth).

Table 2. Landsat-8 scenes used to build the June–July 2024 median composite (Tashkent Region)

No.	Landsat_Scene_ID	Acquisition_Date	Cloud_Cover (%)
1	LC08_153031_20240613	2024-06-13	5.02
2	LC08_153031_20240629	2024-06-29	12.19
3	LC08_153032_20240613	2024-06-13	7.35
4	LC08_153032_20240629	2024-06-29	6.48
5	LC08_154031_20240604	2024-06-04	1.76
6	LC08_154031_20240620	2024-06-20	2.21
7	LC08_154031_20240706	2024-07-06	3.35
8	LC08_154031_20240722	2024-07-22	0.41
9	LC08_154032_20240604	2024-06-04	20.18
10	LC08_154032_20240620	2024-06-20	7.97
11	LC08_154032_20240706	2024-07-06	2.17
12	LC08_154032_20240722	2024-07-22	1.01

Classification algorithms

In this study, two widely used machine learning algorithms — Random Forest (RF) and Support Vector Machine (SVM) — were applied for Land Use/Land Cover (LULC) classification. Both algorithms are non-parametric, capable of handling high-dimensional datasets, and have been extensively validated in remote sensing applications [Huang et al., 2002; Mountrakis et al., 2011; Arpitha et al., 2023].

RF is an ensemble-based algorithm that constructs a large number of decisions trees and aggregates their results through majority voting. Each tree is trained using a bootstrap sample of the training dataset, while at each node only a random subset of predictor variables is considered. This mechanism reduces overfitting and enhances generalization ability [Gislason et al., 2006; Rodriguez-Galiano et al., 2012; Belgiu, Drăguț, 2016]. The classification in RF is determined using the majority voting approach (1):

$$f(x) = \text{majority vote}\{h_1(x), h_2(x), \dots, h_n(x)\} \quad (1),$$

where y — the predicted class label,

$h_i(x)$ — the output of the i^{th} decision tree,

n — is the total number of trees in the forest [Breiman, 2001].

RF is particularly effective in handling noisy data and complex class distributions, making it suitable for heterogeneous landscapes such as the Tashkent Region. RF has become one of the most commonly used classifiers due to its ensemble learning approach, where multiple decision trees are constructed and combined to produce more stable results. Its main advantages include robustness to overfitting, tolerance to irrelevant variables, and computational efficiency. RF also provides variable importance measures, allowing researchers to assess which bands or indices contribute most to classification. However, a known limitation is that RF may be biased toward

classes with larger sample sizes, and in some cases, it may misclassify minority land cover types if the training dataset is imbalanced.

Support Vector Machine (SVM) is a supervised learning algorithm that classifies data by finding the optimal hyperplane that maximizes the margin between different land cover classes. SVM is particularly effective for small sample sizes and high-dimensional data [Cortes, Vapnik, 1995; López et al., 2022]. For a given dataset (x_i, y_i) where x_i is the feature vector and y_i is the class label, SVM (Kernelized SVM) aims to solve the following optimization problem (2):

$$f(x) = \text{sign}\left(\sum_{i=1}^n a_i y_i K(x_i, x) + b\right) \quad (2),$$

where $K(x_i, x)$ — the kernel function (e. g., Radial Basis Function, Polynomial).

In this study, we used RBF kernel, which is (3):

$$K(x_i, x) = \exp(-\gamma \|x_i - x_j\|^2) \quad (3).$$

SVM, on the other hand, excels in cases with smaller training datasets and complex class distributions. By using kernel functions, such as the Radial Basis Function (RBF), SVM can project data into higher-dimensional spaces where classes become linearly separable. This makes SVM particularly effective for distinguishing spectrally similar land cover classes (e. g., croplands vs. forests). Nevertheless, SVM requires careful parameter tuning, specifically the regularization parameter (C) and kernel coefficient (γ), and may become computationally intensive for very large datasets. Despite these challenges, numerous studies have demonstrated its superior accuracy in remote sensing classification tasks.

By employing both RF and SVM, this study not only compares their classification performance but also highlights their respective strengths and limitations. The dual application allows for a more comprehensive evaluation of LULC mapping accuracy in the study area and contributes to methodological transparency for future research.

Accuracy assessment

To evaluate the performance of the classification results, an accuracy assessment was conducted using a confusion matrix derived from the validation dataset. The assessment included the calculation of Overall Accuracy (OA), Kappa Coefficient (KC) for each land cover class. These metrics provide a comprehensive understanding of classification reliability by comparing predicted classes with ground truth labels. To ensure accurate classification and validation, ground truth data were collected from high-resolution Google Earth imagery and field observations. More than 700 sample points were selected and manually classified into six LULC categories. The dataset was divided into 70 % for training and 30 % for validation, ensuring a balanced and statistically significant assessment of classification accuracy. This evaluation ensures the robustness and generalizability of the classification models.

Software and tools

All classification experiments, including Random Forest (RF) and Support Vector Machine (SVM), were carried out in the Google Earth Engine (GEE) cloud platform, which provides access to the full Landsat archive and offers built-in machine learning algorithms (`ee.Classifier.smile RandomForest()` and `ee.Classifier.libsvm()`). This enabled efficient preprocessing, model training, accuracy assessment and sampling processes directly within a cloud-based environment, ensuring

reproducibility and eliminating the need for local data storage or high-performance computing resources. However, GEE’s implementations of RF and SVM have limited parameter tuning compared to Python libraries (e. g., scikit-learn), which might constrain optimization for specific datasets [Sultan et al., 2025]. Built-in preprocessing does not automatically normalize reflectance in mountainous areas, which may affect classification accuracy in regions like northeastern Tashkent [Zhou et al., 2016]. While GEE is powerful for analysis, final visualization and figure preparation required licensed ArcGIS Pro, adding a dependency on commercial software.

For visualization purposes, the classified raster outputs generated in GEE were exported and further processed in ArcGIS Pro (licensed version). ArcGIS was only used for cartographic representation, map layouts, and preparation of figures for publication. All accuracy statistics, including confusion matrices, Overall Accuracy (OA), and Kappa Coefficient (KC), were computed inside GEE. The combination of GEE and ArcGIS ensured both computational efficiency and high-quality visualization. While GEE offers robust scalability for processing large datasets, one limitation is the restricted flexibility for hyperparameter tuning compared to local Python-based workflows.

RESEARCH RESULTS AND DISCUSSION

The Land Use/Land Cover (LULC) classification for the Tashkent Region was performed using Landsat-8 imagery acquired between June and July 2024. Two machine learning algorithms — Support Vector Machine (SVM) and Random Forest (RF) — were implemented and evaluated for classification accuracy. Six major land cover classes were identified: Water, Bare land, Built-up Area, Cropland, Snow, Forest. Ground truth samples were used for supervised classification, and the models were trained using 70 % of the samples, while the remaining 30 % were reserved for validation. The performance of each model was assessed using confusion matrices, overall accuracy (OA), and the kappa coefficient (KC).

The SVM classifier achieved the highest performance with an Overall Accuracy of 96.78 % and a Kappa Coefficient of 0.9604. The Random Forest classifier also performed well, with an Overall Accuracy of 94.95 % and a Kappa Coefficient of 0.9377. These results indicate a strong agreement between the classified outputs and the reference data, with SVM showing slightly better reliability.

Table 3. Overall Accuracy (OA), and Kappa Coefficient (KC) for the classifiers

Metric	RF	SVM
Overall Accuracy	94.95 %	96.78 %
Kappa Coefficient	93.77 %	96.04 %

Confusion matrix analysis revealed that SVM produced fewer misclassifications, particularly in complex classes such as Cropland, and Forest. In contrast, the RF classifier showed slightly higher confusion between Cropland and Forest, as reflected in its error matrix. The higher performance of the SVM classifier can be attributed to its ability to handle high-dimensional data and perform well in cases where class boundaries are not linearly separable. RF, though slightly less accurate, remains a robust classifier known for its efficiency and capability to handle large datasets.

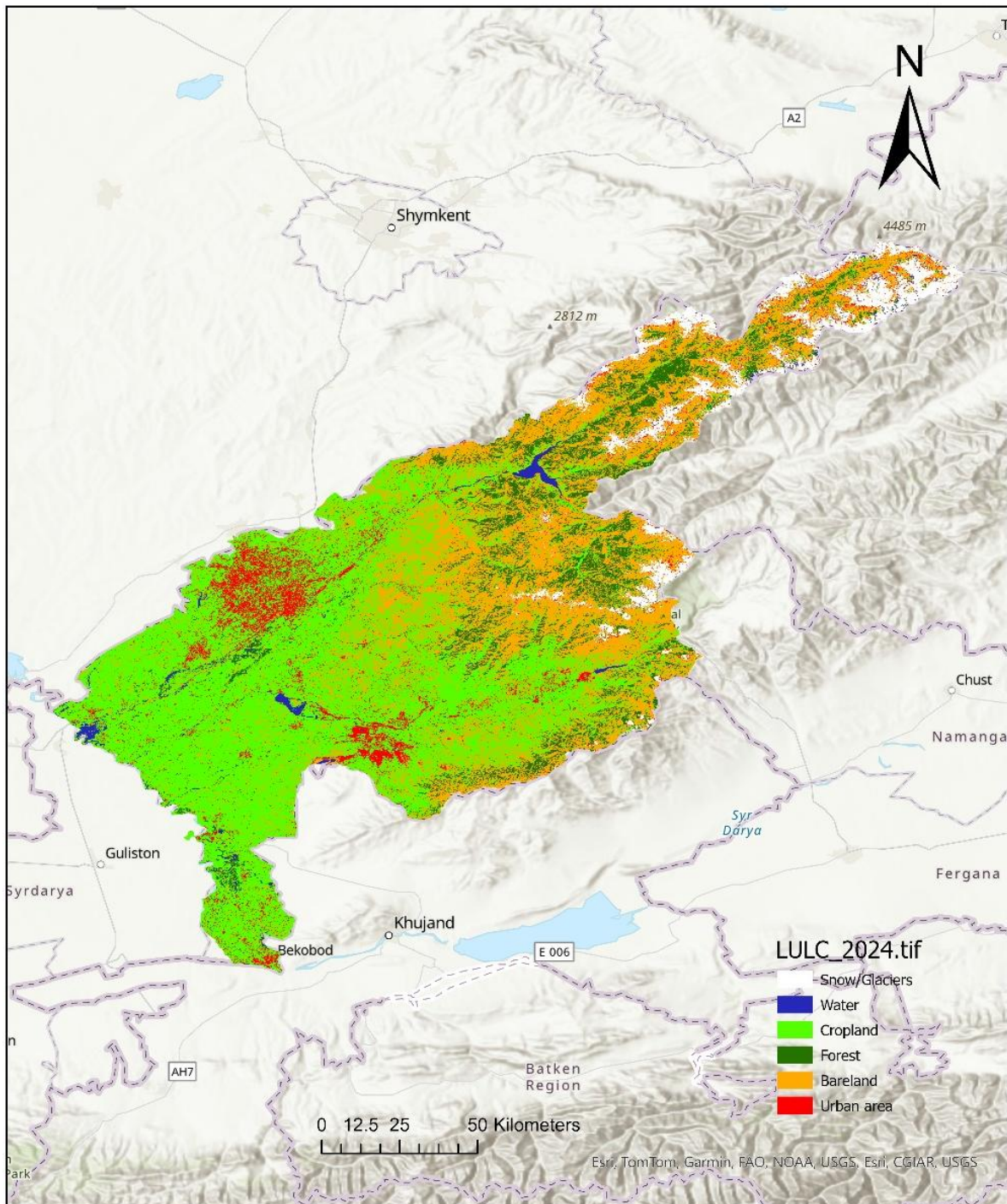


Fig. 2. Land Use/Land Cover (LULC) classification maps of the Tashkent Region generated using Landsat-8 imagery (June 2024). The classifications were performed using Random Forest (RF) algorithm. The map shows seven major classes: Water, Bare land, Built-up Area, Cropland, Snow, Forest

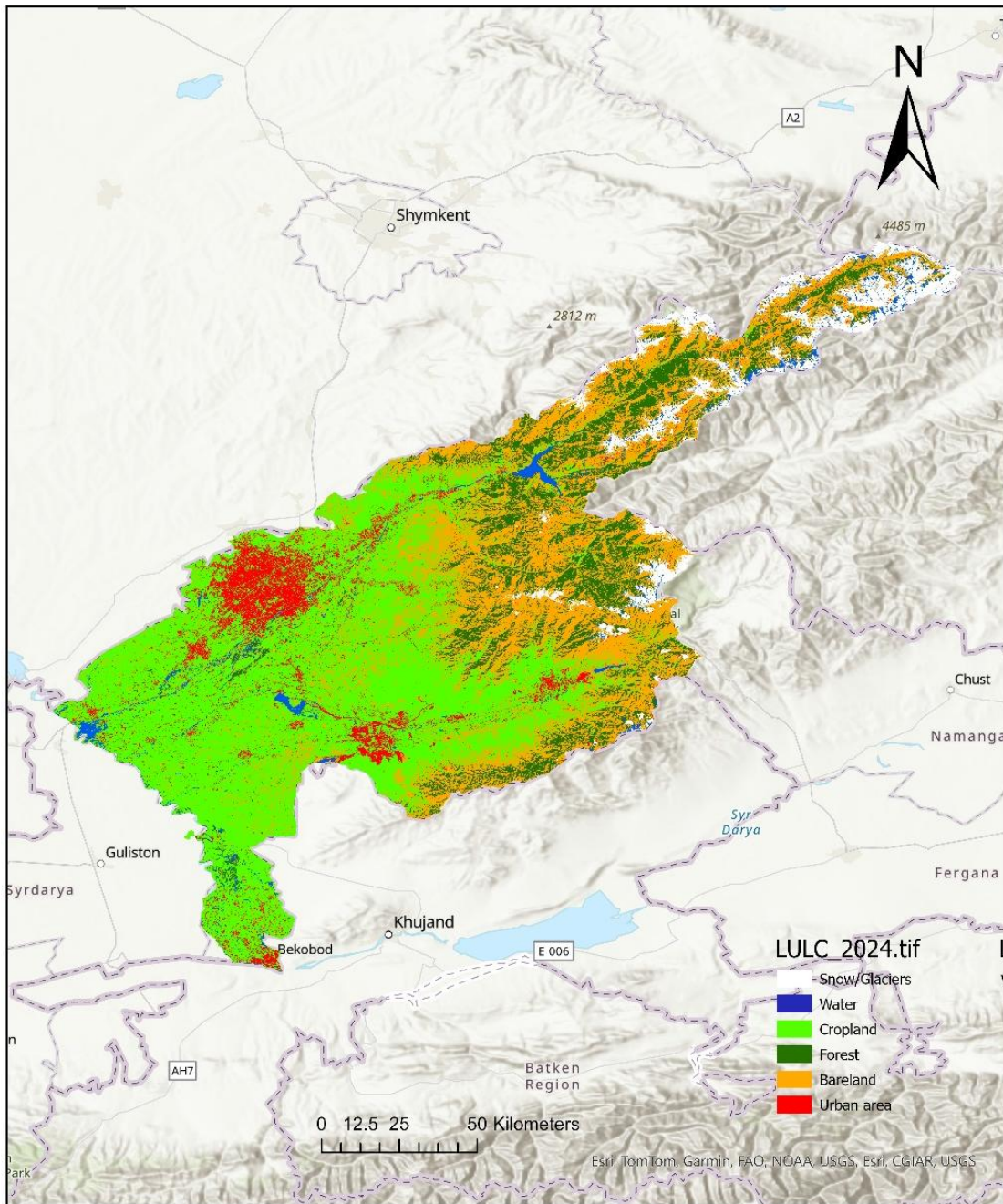


Fig. 3. Land Use/Land Cover (LULC) classification maps of the Tashkent Region generated using Landsat-8 imagery (June 2024). The classifications were performed using Support Vector Machine (SVM)

Table 4. Confusion Matrix for the Support vector machine (SVM) classifier

Actual/Predicted	Water	Bare land	Built-up	Cropland	Snow	Forest
Water	14	0	0	0	0	0
Bare land	0	22	0	0	0	0
Built-up	0	0	43	1	2	2
Cropland	0	0	0	47	0	0
Snow	0	0	0	0	39	0
Forest	0	0	0	0	2	46

Table 5. Confusion Matrix for the Random Forest (RF) classifier

Actual/Predicted	Water	Bare land	Built-up	Cropland	Snow	Forest
Water	14	0	0	0	0	0
Bare land	0	22	0	0	0	0
Built-up	0	0	45	1	2	0
Cropland	0	0	0	47	0	0
Snow	0	0	5	0	34	0
Forest	0	0	2	0	1	45

CONCLUSIONS

The accurate classification of Land Use/Land Cover (LULC) is a foundational component of environmental management, agricultural monitoring, and urban planning. In this study, we assessed and compared the effectiveness of two well-established machine learning algorithms — Support Vector Machine (SVM) and Random Forest (RF) — for classifying LULC types using Landsat-8 OLI satellite imagery for the summer season of 2024 in the Tashkent Region of Uzbekistan. The methodology integrated a comprehensive workflow that included preprocessing steps such as filtering for cloud-free images, selecting relevant spectral bands, clipping to the study region, and using a well-prepared set of ground truth samples representing six dominant LULC classes: water, bare land, built-up areas, croplands, forest, and snow. Classification performance was assessed using confusion matrices, and metrics such as Overall Accuracy (OA) and Kappa Coefficient (KC) were used to evaluate model robustness and reliability.

The results demonstrated that both classifiers provided high classification performance, reinforcing the applicability of machine learning techniques in satellite-based land cover mapping. However, the Support Vector Machine (SVM) classifier outperformed the Random Forest (RF) algorithm, achieving an OA of 96.78 % and a Kappa Coefficient of 0.96, compared to RF's OA of 94.95 % and KC of 0.93. The SVM algorithm showed particularly strong accuracy in distinguishing between spectrally similar classes, such as cropland and forest, which are often difficult to separate using traditional classification techniques. These findings suggest that SVM is more suitable for LULC classification in regions with complex and heterogeneous landscapes, such as the Tashkent Region. The SVM's capacity to work well with high-dimensional input data and its ability to define optimal class boundaries using kernel functions played a key role in delivering superior results. While Random Forest remains a powerful and interpretable classifier with good performance, especially in handling large datasets and noisy variables, it was slightly less precise in this particular case study.

Another important takeaway from this study is the importance of high-quality training data. The performance of both classifiers was heavily dependent on the representativeness and spatial distribution of the training samples. The integration of accurate ground truth data allowed for the development of reliable models, reducing the risk of misclassification and enhancing the generalizability of the results. In addition, the study demonstrated the utility of Google Earth Engine (GEE) as a powerful cloud-based platform for scalable and efficient satellite image analysis. GEE enabled the automation of the workflow, seamless integration of various data sources, and rapid processing of large-scale remote sensing datasets, which is particularly beneficial for research and operational land monitoring in developing regions.

The implications of this study are significant for land managers, policymakers, urban planners, and environmental researchers. High-accuracy LULC maps can support a wide range of applications, including land resource management, monitoring agricultural expansion, deforestation tracking, urban growth assessment, and the evaluation of climate impacts on land systems.

In conclusion, this study provides empirical evidence of the effectiveness of machine learning algorithms in satellite-based LULC classification. The SVM classifier demonstrated strong potential for delivering reliable and precise land cover maps, which can play a pivotal role in supporting sustainable land management strategies and evidence-based decision-making in Uzbekistan and similar regions. As remote sensing technology and machine learning methods continue to advance, their integration will become increasingly vital for addressing pressing environmental and socio-economic challenges in the face of rapid global change.

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